REVIEW ARTICLE

Augmented and Mixed Reality: Technologies for Enhancing the Future of IR

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ABSTRACT

Augmented and mixed reality are emerging interactive and display technologies. These technologies are able to merge virtual objects, in either 2 or 3 dimensions, with the real world. Image guidance is the cornerstone of interventional radiology. With augmented or mixed reality, medical imaging can be more readily accessible or displayed in actual 3-dimensional space during procedures to enhance guidance, at times when this information is most needed. In this review, the current state of these technologies is addressed followed by a fundamental overview of their inner workings and challenges with 3-dimensional visualization. Finally, current and potential future applications in interventional radiology are highlighted.

ABBREVIATIONS

AR = augmented reality, DVR = direct volume rendering, FOV = field of view, HMD = head-mounted display, IPD = interpupillary distance, OST = optical see-through, SR = surface rendering, 3D = 3-dimensional, 2D = 2-dimensional, VR = virtual reality, VST = video see-through

From the 2018 and 2019 SIR Annual Scientific Meetings.

J Vasc Interv Radiol 2019; :1-9

https://doi.org/10.1016/j.jvir.2019.09.020

Spatial computing is a new paradigm of computing that uses the immediate, surrounding environment as a medium to interact with technology. Virtual, augmented, and mixed reality are all types of spatial computing. Virtual reality (VR) completely immerses the user in an artificial, digitally created world. Augmented reality (AR) overlays digital content on the real world, enhancing reality with superimposed information. Mixed reality, also known as merged reality, represents the fusion of both virtual and real-world environments, where digital and physical objects coexist and can interact with each other.

Despite mixed reality devices being an evolution of AR, traditionally, mixed reality represented a continuum with the real-world environment at 1 end of the spectrum to a completely virtual environment at the opposite end (**Fig 1**) (1). This review will consider mixed reality as synonymous with AR and will focus on AR and its potential impact on interventional radiology (IR); VR will not be discussed in detail. Much of the research highlighted has been demonstrated as proof of concept or as a feasibility study; more established studies and clinical trials remain to be published.

One of the key benefits of AR over VR is the ability to visualize and interact with digital objects while maintaining views of the natural world. Preserving direct line of sight with the surrounding environment permits the use of AR during image-guided interventions, provides relevant depth cues, and reduces VR sickness, also known as

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B.J.P. receives grants from the National Institutes of Health (NIH; 5T32EB004311), SIR Foundation, and Nvidia (Santa Clara, California). S.J.H. reports personal fees from BTG (London, United Kingdom) and Amgen (Thousand Oaks, California). C.M. receives grants from Cleveland Clinic Lerner Research Institute and National Center for Accelerated Innovation (NCAI-CC); and is a paid consultant for Boston Scientific (Marlborough, Massachusetts), BTG (London, United Kingdom), and Terumo Medical (Tokyo, Japan). B.J.W. receives grants from Philips (Amsterdam, The Netherlands), Nvidia (Santa Clara, California), Siemens (Munich, Germany), Celsion (Lawrenceville, New Jersey), XACT Robotics (Caesarea, Israel), and BTG (London, United Kingdom), royalties from Philips (Amsterdam, The Netherlands), and research support from the NIH Center for Interventional Oncology and NIH Intramural Research Program. Neither of the other authors has identified a conflict of interest.

Videos 1–3 can be found by accessing the online version of this article on *www.jvir.org* and clicking on the Supplemental Material tab.

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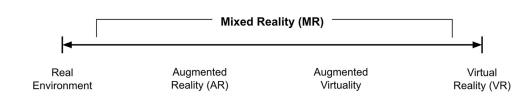


Figure 1. Reality-virtuality continuum proposed by Milgram in 1994 (1).

cybersickness. Cybersickness results from discrepancies between the visual and vestibular senses and can still occur with AR, but is less frequent and milder compared with VR (2).

AR helps increase situational awareness by reducing shifts in focus (3,4). Strategically placed digital content minimizes refocusing between the content and the real world. AR devices can be grouped into multiple, distinct subtypes (Fig 2): head-mounted display (HMD), handheld displays, and stationary displays. These classifications can be further categorized into optical see-through (OST) and video see-through (VST). OST displays use special transparent lenses that allow direct views of the external environment. VST displays use a video feed to indirectly view the external environment. These categories can be further subdivided into monocular or binocular. Monocular displays provide a single channel for viewing. Binocular displays provide 2 separate channels to each eye to simulate the perception of depth through stereoscopy.

An OST display has 3 main components: light engine, optical combiner, and computer (**Fig 3**). Special transparent lenses, called optical combiners or holographic waveguides, merge digitally created images with light from the natural world. The optical combiner acts essentially like a partial mirror, allowing light from the real world to pass through while redirecting light from the projector to generate a hologram. A complete evaluation of OST-HMDs and their applications for surgical interventions is provided by Qian et al (5).

In general, there are 2 conventional methods for rendering 3-dimensional (3D) volumetric data: (i) surface rendering (SR; Video 1 [available online on the article's Supplemental Material page at www.jvir.org]), also known as indirect volume rendering or shaded surface display, and (ii) direct volume rendering (DVR; Video 2 [available online on the article's Supplemental Material page at www.jvir.org]) (6-9). SR is a binary process with visualization of surface meshes at tissue interfaces that are usually preprocessed by segmentation and represent a fraction of the raw volumetric data. DVR is a continuous and much more computationally intensive process involving the entire volume of data, but it provides the most accurate visual 3D representation of medical imaging (9-11). Both of these methods can be incorporated into AR displays to render medical imaging in actual 3D space (9).

The primary advantage of AR displays is the ability to place and anchor virtual objects anywhere in space. This can be useful for projecting anatomic models or 3D imaging through the surgical drape, flat panel detector, or computed tomography (CT) gantry. However, this feature can also unintentionally preclude visualization of important physical objects, such as instruments and the operator's hands (Fig 4). Therefore, object occlusion, or the way virtual objects project in front of and behind physical objects, will be important for managing virtual content in procedural settings (12).

One of the key limitations of AR displays is the field of view (FOV) for augmentation. Naturally, binocular FOV of the human eyes is about 200° in the horizontal plane and 135° in the vertical plane (13). All commercially available OST-HMDs have $<90^{\circ}$ horizontal or vertical FOVs, with most ranging at 30–40° (5). Additionally, most untethered displays have battery lives of 2–3 hours (14), an important factor to consider during prolonged procedures. In general, early clinical studies will seek to define how and whether AR can potentially offer additional benefits in IR, such as enhancing anatomic understanding, decreasing procedure times, and reducing radiation exposure.

3D ACCURACY, TRACKING, AND REGISTRATION

Accurate tracking and registration are needed for any imageguided navigation system (15). For binocular displays, projectional accuracies are dependent on accurate calibration of the device. Calibration of OST-HMDs is necessary to tailor projections to the user's interpupillary distance (IPD) (16). Inaccurate IPD can result in poor eye–lens alignment, image distortion, and eye strain. Additionally, small errors in the IPD as well as off-centering of the device can propagate to large projectional errors resulting from off-axis projection (17).

Near-perfect accuracies are needed for AR to be useful during image-guided interventions. Although measuring accuracies of virtual objects in a 2-dimensional (2D) plane is relatively straightforward, measuring accuracies of virtual 3D objects is more challenging. Accuracy in depth, or the z-plane, is affected by the vergence–accommodation conflict (18). Human eyes naturally converge and focus on an object at the same distance. However, because most OST-HMDs have fixed focal planes, the eyes may focus and converge at separate distances, causing distorted depth perception (**Fig 5**). This conflict is also the leading contributor for causing eye fatigue and discomfort, common symptoms from prolonged AR use (19).

Microsoft HoloLens (Redmond, WA), which was released in 2016, has been shown to be systematically superior to comparative OST-HMDs on the market for surgical

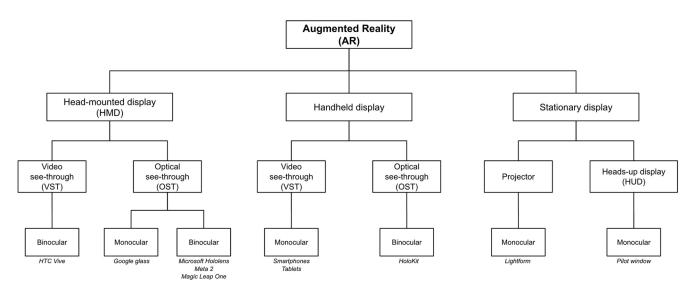


Figure 2. Organizational chart on types of AR devices. Specific examples are displayed in italics where appropriate.

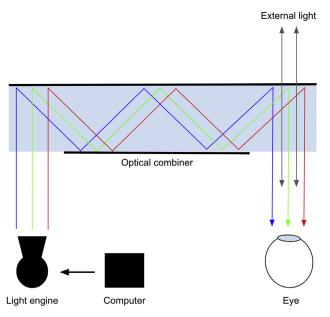


Figure 3. General schematic of an OST display. Light from a projector is reflected through a waveguide using total internal reflection and diffraction and is directed at specific angles and wavelengths into the eye to produce a hologram. External light from the natural world also passes through into the eye.

interventions (5). Several validation studies have reported HoloLens accuracy to be near or within one centimeter (20–25). With subcentimeter accuracies, the US Food and Drug Administration approved Novarad Opensight (American Fort, UT) and Medivis SurgicalAR (Brooklyn, NY) software applications in September 2018 and May 2019, respectively, for preoperative visualization using HoloLens.

Tracking is the sensing and measuring of spatial properties. Registration involves the matching or alignment of those spatial properties, allowing anatomic imaging to be overlaid directly onto the patient. AR devices contain multiple sensors that continuously map and track its position within the environment, a process known as SLAM (26). Accurate mapping and tracking are necessary to update spatial relationships of virtual objects. Full tracking requires 6 degrees of freedom: 3 degrees of freedom in position (x-, y-, and z-axes) and 3 degrees of freedom in rotation (pitch, yaw, and roll) (**Fig 6**). Because AR involves 3D tracking, accurate registration can be challenging and limited by built-in sensors, known as inside-out tracking. However, computer vision algorithms using built-in cameras to detect and track image-based markers can supplement inside-out tracking and provide accurate and fast registration (20,21,27–29).

Many existing AR-assisted navigation systems integrate an external optical tracking system, or outside-in tracking, and bypass internal sensors to further improve accuracies or track additional hardware (30-36). Another external tracking system commonly used is electromagnetic tracking (37). Despite the type of tracking, most external tracking systems provide limited degrees of freedom, balancing tradeoffs between sensing position and orientation. For integration with external trackers, each coordinate system needs to be calibrated and transformed to be congruent within the same space, or world coordinate system (Fig 7). Calibration of the AR device and external trackers can be performed using manual, semiautomatic, or automatic methods (32,38). Once calibrated, 3D datapoints in virtual space can be registered to known and tracked points in physical space.

The aforementioned registration processes have all been based on rigid transformations. However, multiple practical considerations impede accuracy and rigid registration, such as patient motion, breathing, and organ deformation, which are dynamic processes that may require dynamic and potentially computationally intensive solutions (39,40). Respiratory and patient motion continue to remain 1 of the largest technical and practical hurdles for adoption of many

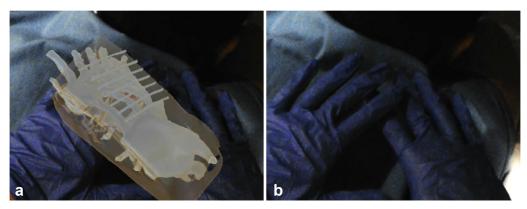


Figure 4. Object occlusion as a potential unintended consequence of AR. (a) Virtual model within the patient projecting through the operator's hands, unintentionally occluding visualization of the hands. (b) Hands are visualized with hologram turned off.

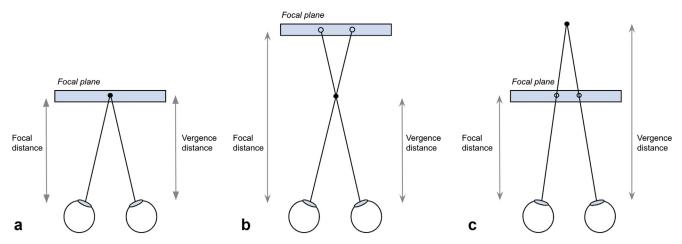


Figure 5. Various visual perception scenarios affecting vergence and accommodation. (a) Focal distance and vergence distance are equal, which occurs naturally with human vision. This is the ideal configuration for OST-HMDs. (b) Vergence–accommodation conflict with focal distance greater than vergence distance when virtual objects are projected close to the display. (c) Vergence–accommodation conflict with focal distance less than vergence distance when virtual objects are projected far from the display.

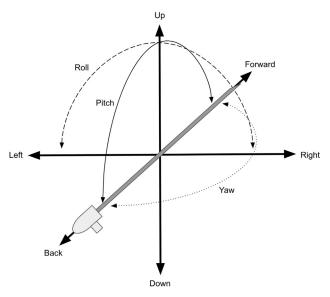


Figure 6. Six degrees of freedom representing combination of 3 positions (x-y-z) and 3 orientations (roll-pitch-yaw).

navigation or fusion systems in IR, with many systems opting for simple respiratory gating (41) or a rigid to elastic switch (35).

AR IN MEDICINE

The enhanced ability of AR to visualize and localize targets may have downstream implications for improving procedural outcomes, complication profiles, and operating time. Thus, AR has been explored to augment a variety of surgical procedures. Recent applications with AR technologies have been demonstrated in neurosurgery (25,33), otolaryngology (42), vascular surgery (43), hepatobiliary surgery (44), orthopedic surgery (45), plastic surgery (14), and urology (46). Despite the importance of visualizing and localizing targets in IR, a recent systematic review of wearable headsup displays in an operating room identified IR as having the fewest number of published studies among 10 other procedural specialties (47). As image-guided experts and proceduralists, more experimentation and developments in IR

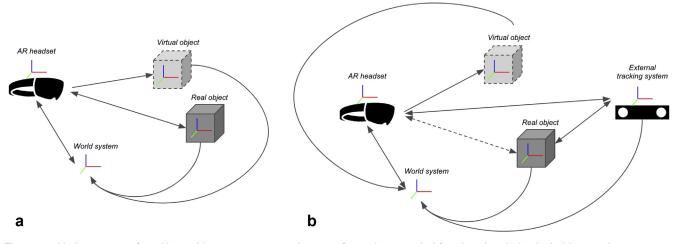


Figure 7. Various types of tracking, with arrows representing transformations needed for virtual and physical objects to be congruent within the same space. Red-green-blue axes represent respective coordinate systems. (a) Inside-out tracking using built-in sensors within the augmented reality headset. (b) Outside-in tracking after integration with an external tracking system. Tracking of real physical objects by the AR headset (dotted line) is replaced by the external tracking system.

should be undertaken to evaluate this new visualization technology as other specialties have done.

IR APPLICATIONS

The role for advanced imaging and technologies in imageguided procedures has transformed procedural medicine. The 1996 Radiological Society of North America New Horizons Lecture emphasized the capability for computers to enhance visibility and navigate through 3D coordinates during IR and minimally invasive procedures (48). The lecture highlighted the promises of preoperative planning to select optimal approaches, register models onto patients, and display virtual needle paths, all of which continue to be active areas of research and applicable to a variety of IR procedures. More than 2 decades later, these promises still have yet to be fully realized, but current research endeavors show progress and potential for translation into the IR suite.

Endovascular Procedures

The additional spatial information provided by AR can enable the interventional radiologist to obtain a more intuitive understanding of complex vascular anatomy. Currently, interventional radiologists must cognitively associate 2D images on a monitor screen with a mentally reconstructed 3D model. AR permits the ability to easily visualize 3D vascular anatomy from prior cross-sectional imaging for preprocedural planning (49) or use as an intraprocedural reference (50). This capability can alleviate the continual process of associating and mentally reconstructing 2D images into 3D (51). Indeed, cognitive reconstruction and registration have been shown to be less accurate than registration with computer assistance for fusion-guided, needle-based interventions (52).

With AR, the interventional radiologist can look virtually inside the patient from any viewpoint. Anterior, posterior, and oblique divisions of vessels can be easily differentiated and optimally displayed with the added depth dimension (51). Before the procedure, the interventional radiologist can simulate ideal fluoroscopic angles and positions that highlight vessel courses and branchpoints. During the procedure, a virtual 3D roadmap can be placed anywhere within the IR suite as a reference to augment vessel selection and catheter positioning. Acquired cone-beam CT, or rotational angiography, can also be projected in 3D to quickly confirm the target of interest, as opposed to scrolling though axial 2D images.

AR utilization may also help achieve radiation dose savings during endovascular procedures in the future. Using AR and external electromagnetic tracking, Kuhlmann et al (53) demonstrated the ability to overlay a 3D vascular model on a patient phantom and virtually track and navigate an endovascular catheter through the vascular model, foreseeably eliminating the need for any radiation for real-time endovascular guidance.

Percutaneous Procedures

Many AR implementations currently exist for navigation during percutaneous needle-based interventions. For example, virtual 3D needle trajectories can be registered to patients to assist in the placement and positioning of ablation probes (**Fig 8**); protocol approved by the institutional review board at the University of Pennsylvania. Moreover, AR has been shown to reduce procedure times, number of acquired images, and radiation dose during simulated percutaneous bone interventions (54). In a similar fashion, fusion navigation with electromagnetic tracking has been proven in a randomized controlled trial to reduce radiation, number of CT scans, indwelling needle time, and the number of needle manipulations in CT-guided liver biopsies (55). A clinical trial using HoloLens for percutaneous liver ablation is currently under way (**Fig 9**) (56); this protocol is

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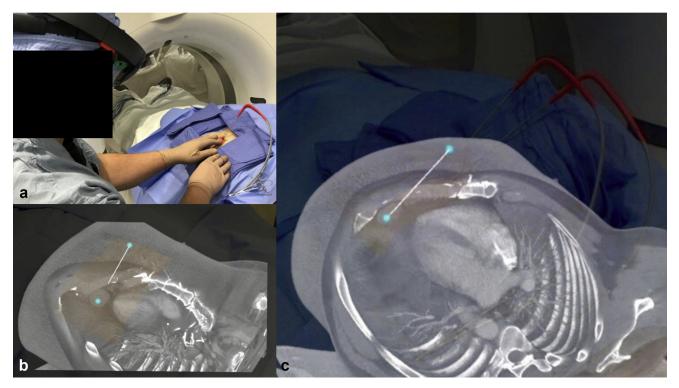


Figure 8. (a) Metastatic thymoma for cryoablation of cardiophrenic lymph node using AR-assisted visualization intraoperatively. Preoperative CT was projected using Microsoft HoloLens (Redmond, WA) and Medivis SurgicalAR (Brooklyn, NY). Rendering was performed on a remote workstation and wirelessly streamed to HoloLens in real time. Holographic 3D volume was manually registered to the patient using the patient's nipples as markers. (**b-c**) A virtual needle trajectory track can be overlaid during planning and used as a virtual guide during the procedure.

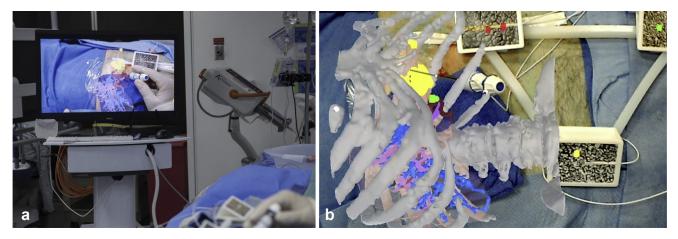


Figure 9. (a) Hepatocellular carcinoma for microwave ablation using intraoperative AR-assisted navigation. The preoperative CT was projected using surface rendering software and navigation system by MediView XR (Cleveland, OH) and Microsoft HoloLens (Redmond, WA). The holographic projection was registered to the patient using an electromagnetic tracking system and image-based markers. (b) Combined real-time tracking of virtual/actual ablation probe relative to tumor target (yellow).

approved by the institutional review board at the Cleveland Clinic.

One of the first AR systems for this application was made by Siemens (Erlangen, Germany) in 2006 and called RAMP, which used a VST-HMD system to project virtual needle trajectories during CT- and magnetic resonance imaging– guided interventions (57,58). More recent AR-assisted navigation systems have been developed using tablets and OST-HMDs. An AR-assisted needle guidance system using an OST-HMD and external optical tracking demonstrated guidance error between the actual and virtual needle trajectories by less than 2° in a CT phantom (31). Another system using a tablet computer and computer vision marker detection achieved sub-5-mm accuracies in a porcine model and cadaver for liver thermal ablation (28), which has been subsequently upgraded with a VST-HMD and

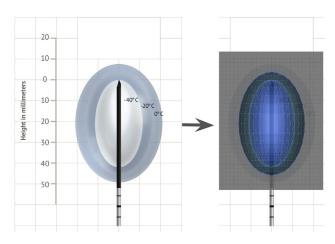


Figure 10. Planning an ablation with augmented reality. 3D surface-rendered model of -40° C and -20° C isotherm ice balls from manufacturer technical specifications from Galil Medical (Arden Hills, MN).

commercialized as Bracco Imaging Endosight (Milan, Italy) for CT-based tumor ablations. In contrast to these rigid needle-based navigation systems, HoloLens was used to project and extrapolate bending 3D needle trajectories with a shape-sensing needle and reduced targeting error by 26% compared with rigid needle assumptions (32).

AR can provide enhanced volumetric tumor margin visualization and localization, potentially leading to more successful ablation coverage and adequate treatment margins (59). Higher ablation success rates have been shown in simulated microwave liver ablation following planning on 3D models, albeit on a monitor screen, compared to 2D image slices (60). In a similar fashion, AR may help plan and facilitate optimal probe placement by visualizing theoretical ablation treatment volumes in actual 3D space (Fig 10 and Video 3 [available online on the article's Supplemental Material page at *www.jvir.org*]). These plans can then be transferred and registered onto the patient for virtual procedural guidance using the planned trajectories. This approach may give more confidence to the interventional radiologist for approaching and treating targets in challenging locations that were previously unfavorable, such as liver dome lesions requiring nonorthogonal or outof-plane approaches (15).

AR may be able to help achieve considerable radiation dose savings and resource utilization during percutaneous procedures. The use of an AR capable C-arm system revealed approximately 40%–50% radiation dose reduction during needle localization of targets in pigs compared with standard CT fluoroscopy while preserving accuracy (61). HoloLens and Novarad OpenSight were used to virtually guide spinal needles into a lumbar spine phantom and resulted in sub-5-mm accuracies using preoperative CT alone without the need for any real-time imaging (24).

Training and Instruction

Simulations with AR for medical training are becoming increasingly popular for teaching procedural and technical

skills (62). AR can help create immersive scenarios within a real IR suite to improve performance before complex cases or simulate the use of new equipment before actual use (63,64). However, current evidence regarding the relative superiority of AR simulations to conventional instruction is lacking. One study found no difference in internal jugular vein cannulation time and total procedure time using AR compared to conventional instruction (65).

In addition to simulations, AR devices enable the ability to share environments for collaborative experiences with other users. Existing interactive platforms allow remote consultants to project live annotations into the AR display of another operator, offering remote real-time instruction or expert assistance (66,67). Additionally, procedures performed with AR HMDs can be broadcasted on a larger scale, allowing interventional radiologists in rural settings or developing countries to visualize live or recorded procedures performed by experts (68).

Ergonomics and Workflow

There are benefits to projecting virtual 2D objects as well as 3D objects in IR. AR headsets are able to deploy virtual 2D monitors that can improve ergonomics, patient monitoring, and workflow. Virtual 2D monitor screens, as many as needed, can be placed anywhere within the IR suite for readily accessible viewing. These virtual screens can be made as large as desired but will fundamentally be constrained by the headset's FOV. Images from the C-arm or ultrasound (US) machine can be streamed to the AR headset in real time with a video capture device (30). This allows the operator to maintain focus on the task at hand while reducing gazes away from the procedural field. For example, virtual 2D monitors placed within the procedural field during vertebroplasty can allow the interventional radiologist to have close observation of cement placement without shifting focus (69). A randomized control trial in breast phantoms showed that AR-assisted needle guidance using a VST-HMD and a virtual screen displaying live 2D US images along the end of the US transducer led to improved biopsy needle accuracy compared with standard US guidance (70).

Finally, AR can have beneficial effects on all IR staff members. C-arms requiring manual positioning can be cumbersome and require several adjustments until the desired view is obtained. An AR-assisted virtual C-arm positioning guide can aid technologists to quickly establish desired C-arm views, eliminating the need for iterative refinement and thereby reducing radiation (71). Additionally, AR can be used to project a radiation dose map of the patient onto the IR table as well as help virtually and visually monitor radiation dose to staff members during the procedure in real time (72). Furthermore, the advent of virtual screens and controls permits the removal of extraneous cables, carts, and mounts to allow staff members to more easily maneuver around the IR suite.

In conclusion, augmented and mixed reality are novel display technologies that are able to provide a new way to

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visualize images and localize targets during image-guided procedures. Although IR has been somewhat slow to adopt such technologies, these technologies may be appealing to interventional radiologists and image-guided therapists for readily accessible image viewing or advanced 3D visualization intraprocedurally. AR-assisted systems should be further developed and evaluated to see if they can improve outcomes in IR with safer, more efficient procedures that require less radiation. Clinical evidence is currently lacking, but as these technologies evolve, AR may become easier to implement and use imaging in an actual volumetric fashion to enhance interventions. However, it will be paramount that metrics be established and clearly defined through validated, high-level, evidencebased studies. In doing so, translation and adoption into the IR suite may transform the way future image-guided interventions are undertaken and provide benefits to patients, operators, and staff.

ACKNOWLEDGMENTS

Special thanks to Dr. Steven Horii and the Penn Medicine Medical Device Accelerator for supporting equipment for AR-related research.

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